ABSTRACT

       Frames comprise odd fields and even fields.
The frame sync segments of the odd fields contains a

5 current map specifying the location of data in frames, a
next map specifying the location of data in a future
frame, and a frame count designating the future frame.
The frame sync segments of the even field may contain the
same information. Alternatively, the frame sync segments

10 of the odd fields contain the current map and part of the
frame count, and the frame sync segments of the
corresponding even fields contain the next map and the
rest of the frame count. A receiver uses the map and
frame count information to find data in the fields of

15 received frames.